

General gearbox data	Character	Unit	
Planetary gearbox - gearing type	-	-	Straight teeth
Rotation direction	-	-	Input and output in the same direction
Number of stages	p	-	2-stage
Output shaft bearing	-	-	Inclined roller bearings
Service Life (L10h)	t _L	h	30.000
Max. operating temperature	T _{min} / T _{max}	°C	-25 / +90
Protection class	-	-	IP 65
Lubrication (lifetime lubrication)	-	-	Standard lubrication (KLübersynth GE 14-112)
Installation position	-	-	Any
Max. bending moment based on the gearbox input flange (for motor weight) (1)	M _b	Nm	8
Motor shaft concentricity / Coaxiality and axial runout Motor flange	-	mm	0,03 / 0,06 (Measuring methods according to DIN EN 50347)
Required motor shaft tolerance	-	-	j6; k6
Min. permissible motor shaft length	L _{20 min}	mm	11
Reference operating mode	-	-	S1
Reference operating factor	K _A	-	1
Reference speed	n ₂	rpm	100
Reference ambient temperature	T _{Amb}	°C	20
Radial force for output bearing based on shaft end after L10h=20,000h with Fa=0N	F _{r 20.000h}	N	2300
Axial force for output bearing based on gearbox axis after L10h=20,000h with Fr=0N	F _{a 20.000h}	N	2850
Radial force for output bearing based on shaft end after L10h=30,000h with Fa=0N	F _{r 30.000h}	N	2000
Axial force for output bearing based on gearbox axis after L10h=30,000h with Fr=0N	F _{a 30.000h}	N	2500
Maximum radial force based on shaft end and T2=0Nm	F _{r Max}	N	2700
Maximum axial force based on gearbox axis and T2=0Nm	F _{a Max}	N	2850

(1) Max. motor weight* in kg = $\frac{0,2 \times M_b}{\text{motor length in m}}$

- * with symmetrically distributed motor weight
- * with horizontal and stationary mounting

Ratio-dependent gearbox data	Character	Unit									
Ratio	bii	-	9	12	15	16	20	25	32	40	64
Nominal output torque	T _{2N}	Nm	44	44	44	44	44	40	44	40	18
Max. output torque for 30,000 output shaft rotations	T _{2max}	Nm	70	70	70	70	70	64	70	64	29
Emergency stop torque permitted 1000 times	T _{2Stop}	Nm	88	88	88	88	88	80	88	80	80
Average idle torque for n1=3,000 rpm and 20 °C gearbox temperature	T ₀	Nm	0,3	0,25	0,2	0,2	0,2	0,15	0,15	0,15	0,15
Average thermal input speed at 50% T2N, S1, and T_Amb Operating temperature may not be exceeded!	n _{1N 50%}	rpm	4500	4500	4500	4500	4500	4500	4500	4500	4500
Average thermal input speed at 100% T2N, S1, and T_Amb Operating temperature may not be exceeded!	n _{1N 100%}	rpm	4500	4500	4500	4500	4500	4500	4500	4500	4500
Max. mechanical input speed Operating temperature may not be exceeded!	n _{1 Limit}	rpm	7500	7500	7500	7500	7500	7500	7500	7500	7500
Torsional backlash based on output shaft	j _t	arcmin	< 12	< 12	< 12	< 12	< 12	< 12	< 12	< 12	< 12
Torsional stiffness based on output shaft	c _g	Nm/arcmin	9,3	10,9	9,6	11,3	11,1	11,5	10,9	11,3	7,3
Efficiency at T2N, gearbox temperature 70 °C and n1=1,000rpm	η	%	96	96	96	95	95	95	95	95	91
Running noise at n1=3,000 rpm without load at a distance of 1m	Q _g	dB(A)	60	60	60	60	60	60	60	60	60
Gearbox weight	m _G	kg	1,55	1,55	1,55	1,55	1,55	1,6	1,6	1,6	1,6
Mass moment of inertia based on clamping system diameter input	J	kgcm²	0,132	0,124	0,08	0,088	0,077	0,076	0,067	0,067	0,066

Subject to modifications.



NGV064-bii-SSSD3AC -R(D20)